

# The generation of stable project plans

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**Abstract.** This text summarises the PhD thesis that Roel Leus presented to obtain the degree of Doctor in Applied Economics at the Katholieke Universiteit Leuven, in September 2003. The promotor of the thesis was professor Willy Herroelen. The thesis is written in English and is available from the author's website.<sup>1</sup> The goal of the thesis was to provide recommendations for the detailed scheduling of multi-project organisations, when a certain degree of uncertainty exists about a number of characteristics of the project. Up till now, the majority of the literature on project scheduling has consisted of deterministic models for planning a single project: both the uncertainty aspect as well as the intrinsic difficulty of coordination of a portfolio of projects have been largely ignored.

**Key words:** Project scheduling, uncertainty, robustness, multi-project organisations

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## 1 Introduction and general outline

Projects in a multi-project organisation are interdependent, primarily because they use a joint pool of resources. The central theme of the PhD thesis of Leus (2003) is the concept of *stability*, a quality that is associated with a schedule when this schedule is able to suppress propagation of disruptions, both within the individual project as well as towards other projects. In this way, we attempt to obtain a maximum degree of independence between and within individual project schedules. Stability is a specific form of *robustness*: a robust schedule is protected as well as possible against uncertain events that can occur during the execution of the project

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<sup>1</sup> <http://www.econ.kuleuven.ac.be/tew/academic/prodbel/people/Roel/>

– some examples are bad weather conditions, illness of workers, changing project specifications, ...

The aim of the thesis was to formulate recommendations for the detailed scheduling of multi-project organisations when a certain degree of uncertainty exists about a number of characteristics of the project. We have especially focused on the problem of scheduling projects when stochastic durations are assigned to the individual project activities. Up till now, the majority of the literature on project scheduling has consisted of deterministic models for scheduling a single project, and both the uncertainty aspect as well as the intrinsic difficulty of coordination of a portfolio of projects have been largely neglected: various authors consider multi-project scheduling simply as the scheduling of one large project with as sole objective the construction of a feasible plan with minimum length. However, the different projects that are ongoing in parallel at any particular moment have differing objectives and are each evaluated separately on the way in which they live up to these objectives – every project has separate deliverables and will be evaluated based on the timeliness, quality and cost of those deliverables.

This qualitative insight is the starting point of the thesis and we have tried to translate this intuition into a number of technical scheduling and resource allocation models that allow to focus attention on quantitative implications on the *time* dimension of project performance. The central idea is that, although we normally desire to complete each project by itself as quickly as possible, we sometimes have to make concessions for reasons of coordination and broader organisational goals. This is achieved by implicit or explicit insertion of small ‘buffers’ at various places throughout the scheduling horizon. In this way, an integrated plan that covers the different projects is most valuable.

## 2 Structure and detailed contents of the text

The first chapter of the text provides a general introduction to project planning and draws some parallels between project planning and job shop planning. One of the main lessons to be learnt is that scheduling resources to 100% utilisation will inevitably lead to major delays and queuing when only the slightest amount of uncertainty is present (cfr., Adler et al. 1995, 1996 and Levy and Globerson 1997).

The second part of the thesis (Chapt. 2) presents a classification and survey of the literature on single-project planning with uncertainty, attempting to put order to the vast number of articles that do not always explain how they fit in with the mostly unorganised existing body of research. Most of the material in this chapter can also be found in Herroelen and Leus (2003a).

A third part of the thesis is devoted to the development of stable schedules, with the minimisation of expected deviations in starting times as objective. This work is the most technical part of the text and encompasses Chaps. 3, 4 and 5 (this material is also available as Herroelen and Leus 2003b, Leus and Herroelen 2002 and Leus and Herroelen 2003). Exact algorithms and complexity analysis are provided,

and we also examine the associated problem of resource allocation, again geared especially towards guaranteeing stability. We have not proposed solutions to joint scheduling and resource allocation decisions, but we have pointed out why such integrated solutions are very hard, both from mathematical and managerial points of view. Chapter 3 and part of Chapt. 4 investigate the development of schedules that anticipate one or a minor number of disruptions. This is applicable when the number of disruptions is limited (as opposed to a chaotic environment, where planning is not management's primary concern, but rather 'fire-fighting' and variability reduction). Single-disruption models are especially appropriate for *project* scheduling because the extensive use of human resources makes it possible to actively prevent cumulation of disruptions, whereas machine resources will have independent stochastic breakdowns. Chapter 5 examines detailed resource allocation, which is performed after scheduling has taken place, in line with the hierarchical planning framework of De Boer (1998).

The fourth part of this text is an extensive study of the 'Critical Chain' methodology for project management (CCPM), proposed by Goldratt (1997) (results of our study of the merits and pitfalls of CCPM have been published in Herroelen and Leus 2001 and Herroelen et al. 2002; we also refer the reader to Elmaghraby et al. 2003). The methodology offers valuable insights for the management of project environments with variable activity durations. It is recognised that *duration estimates* of activities are very important, since stochastic quantities are essentially captured by a single deterministic value. From an analysis of the behaviour of human resources, it is concluded that individual activity duration estimations regularly contain protection from variability. The problem is that this protection is not clearly visible or even identified, and often wasted. CCPM advocates the use of aggressive duration estimates (median or average durations) and the explicit inclusion of protection time at strategic places in the schedule, which can be actively monitored and controlled. In line with de Boer (1998), it is advocated that 'slack' be used in a controlled way: it must be quantified and made visible to management.

Unfortunately, scheduling issues are not allotted an appropriate role in most of the sources describing the CCPM-methodology. Those sources spend a lot of time explaining variability and stochastics, which is a good thing, but they do not give enough attention to the combinatorial implications of resource constraints, the very aspect the method is meant to tackle in the first place, the 'critical chain' being a 'resource-constrained critical path'.

Finally, a fifth part of this thesis has attempted to propose planning solutions for multi-project environments on the basis of the experience gained in the preceding pieces of the text. This synthesis contains a classification of multi-project planning environments and provides hints as to which situations are best served by which planning techniques, including guidelines for the choice between stable and active schedules. A short version of this part of the text also appears in Herroelen and Leus (2003c).

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